



MICROCOPY RESOLUTION TEST CHART
MATIONAL BUREAU OF STANDARDS-1963-A

MRC Technical Summary Report #2610

NORMAL MODES OF A LAGRANGIAN SYSTEM CONSTRAINED IN A POTENTIAL WELL

V. Benci

Mathematics Research Center
University of Wisconsin—Madison
610 Walnut Street
Madison, Wisconsin 53705

December 1983

(Received November 8, 1983)



Approved for public release Distribution unlimited

Sponsored by

U. S. Army Research Office

P. O. Box 12211

Research Triangle Park North Carolina 27709

DTIC FILE COPY

84 02 15 165

UNIVERSITY OF WISCONSIN-MADISON MATHEMATICS RESEARCH CENTER

NORMAL MODES OF A LAGRANGIAN SYSTEM CONSTRAINED IN A POTENTIAL WELL

V. Benci*

Technical Summary Report #2610 December 1983

ABSTRACT

Let $a, U \in C^2(\Omega)$ where Ω is a bounded set in \mathbb{R}^n and let (*) $L(x,\xi) = \frac{1}{2} a(x) |\xi|^2 - U(x), \quad x \in \Omega; \quad \xi \in \mathbb{R}^n.$

We suppose that a,U>0 for $x\in\Omega$ and that

 $\lim_{x\to 3\Omega} U(x) = +\infty.$

Under some smoothness assumptions, we prove that the Lagrangian system associated with the above Lagrangian L has infinitely many periodic solutions of any period T.

AMS (MOS) Subject Classifications: 34C25, 70K99, 58E05

Key Words: Lagrangian system, periodic solutions, minimax principle, Palais-Smale condition

Work Unit Number 1 (Applied Analysis)

^{*}Dipartimento di Matematica, Universita di Bari, Bari, Italy

SIGNIFICANCE AND EXPLANATION

The question of existence and the number of periodic solutions (normal modes) for a classical mechanical system is a problem as old as the field of analytical mechanics itself. The development of the nonlinear functional analysis has renewed interest in these problems. In this paper we considers a mechanical system which is constrained in a potential well. We suppose that the dynamics of the system is described by the Lagrangian

$$L(x,\xi) = \frac{1}{2} a(x) |\xi|^2 - U(x), x \in \Omega, \xi \in \mathbb{R}^n$$

where Ω is a bounded open set in \mathbb{R}^n , and a,U $\in C^2(\Omega)$ are positive functions with

$$\lim_{x \to 0} U(x) = +\infty$$

Under some technical assumptions on a and U we prove that our dynamical system has infinitely many periodic solutions of any period T > 0.

Access	on For		
NTIS (DTIC TA Unanno Justif	AB		
Avail	bution/ ability Co	des	(11)
Dist A-	Avail and/o	r	

The responsibility for the wording and views expressed in this descriptive summary lies with MRC, and not with the author of this report.

NORMAL MODES OF A LAGRANGIAN SYSTEM CONSTRAINED IN A POTENTIAL WELL

V. Benci*

1. INTRODUCTION AND MAIN RESULTS.

Let a,U + R where Ω is an open set in R^n . We make the following assumption

 (L_0) Ω is bounded and its boundary is C^2 .

 (L_1) $v \in c^2(\Omega)$

 (L_2) lim $U(x) = +\infty$

(L₃) $\lim_{x\to\partial\Omega} \frac{\nabla U(x) \cdot v(x)}{U(x)} = +\infty \text{ where } v(x) = -V \operatorname{dist}(x,\partial\Omega)$

 (L_4) acc² $(\vec{\Omega})$

 (L_S) a(x) > 0 for every $x \in \Omega$

 (L_6) for every $x \in \partial \Omega$ such that a(x) = 0, $\nabla a(x) \neq 0$.

We consider the Lagrangian

(1.1) $L(x,\xi) = \frac{1}{2} a(x) |\xi|^2 - U(x),$

 $x \in \Omega$, $\xi \in T_{\Omega} = \mathbb{R}^{n}$, and $|\cdot|$ denotes the norm in \mathbb{R}^{n} ,

and we look for normal modes of the dynamical system associated to this Lagrangian; i.e. periodic solutions of the following systems of ordinary differential equations:

(1.2)
$$\begin{cases} \gamma \in c^{2}(\mathbb{R},\Omega) \\ a(\gamma)\dot{\gamma} = \frac{1}{2} |\dot{\gamma}|^{2} \nabla a(\gamma) - (\nabla a(\gamma) \cdot \dot{\gamma})\dot{\gamma} - \nabla U(\gamma) \end{cases}$$

where "•" denotes $\frac{d}{dt}$ and "•" denoted the dot product in \mathbb{R}^n . We restrict our attention to periodic solution of a given period T, and in order to simplify the notation we suppose T = 1. Also it is not restrictive to suppose that

 (L_7) U(x) > 0 for $x \in \Omega$ and $\min U(x) = 0$. $x \in \Omega$ The main result of this paper is the following theorem

^{*}Dipartimento di Matematica, Universita di Bari, Bari, Italy

Sponsored by the United States Army under Contract No. DAAG29-80-C-0041.

Theorem 1.1. If $(L_1)^{-}(L_7)$ hold then the equation (1.2) has infinitely many periodic distinct solutions of period 1. More exactly there exists a positive integer N_0 and two positive constants E^+ and E^- such that for every $N > N_0$ there exists $\gamma_N \in C^2(\mathbb{R},\Omega)$ such that

- (i) γ_N is solution of (1.2)
- (ii) γ_N has period $\frac{1}{N}$
- (iii) $E^-N^2 \leq E(\gamma_N) \leq E^+N^2$

where $E(\gamma) = \frac{1}{2} a(\gamma(t)) |\dot{\gamma}(t)|^2 + U(\gamma(t))$ is the "energy" of γ .

(iv)
$$\alpha N^2 \leq J(\gamma_N) \leq \beta N^2$$

where $J(\gamma_N) = \int \alpha(\gamma_N) |\hat{\gamma}|^2 - U(\gamma_N) dt$ and α and β are constant which depend only on Ω (but not on U and N). Moreover if $U(x_M) = 0$ (i.e. x_M is a minimum point) and $U(x) = o(|x - x_M|^2) \quad \text{for } x + x_M ,$

then we can choose $N_0 = 1$.

Remarks I. Notice that (ii) does not say that $\frac{1}{N}$ is the minimal period of γ_N . It might happen that γ_N has a smaller period. Thus it may happen that $\gamma_N = \gamma_M$ for some $M \neq N$. However (iii) implies that if M >> N then $\gamma_M \neq \gamma_N$.

II. As easy one-dimensional examples show it is possible that equation 1.2 has no periodic solution with minimal period 1.

III. Assumption (L_3) which may appear as the less natural one, describes the behaviour of U(x) as $x + \partial \Omega$. It says that U(x) cannot "oscillate" too badly near the boundary.

IV. We have decided to consider Lagrangian of the form (1.1) (i.e. with a(x) not identically 1 and in particular with a(x) which may degenerate on $\partial\Omega$) because in this way theorem 1.1 can be applied to the study of closed geodesic for the Jacobi metric (which degenerates for $x + \partial\Omega$), cf. $\{B_2\}$.

V. By the proof of the theorem it will be clear that the same result hold for a Lagrangian of the form

$$L(x,\xi) = \sum_{i,j} a_{i,j}(x) \xi_i \xi_j - U(x)$$

with $\sum_{i,j} a_{i,j}(x) \xi_i \xi_j > a(x) |\xi|^2$ and satisfies (L_4-L_6) . More in general, the same method

apply also to the case in which Ω is a Riemann manifold with a C^2 -boundary. We have decided to consider a simpler case in order to not make the notation and the uninteresting technicalities too heavy.

VI. The results of theorem 1.1 holds also if a and U are of class C^1 (cf. remark II after theorem 2.3). However, in order to not get involved in technicalities which will obscure the main ideas we have preferred to treat the C^2 -case.

The study of normal modes of nonlinear Hamiltonian or Lagrangian systems is an old problem which in the last years has attracted new interest. We refer to $\{R_1\}$ for recent references on this subject. However, as far as I know there are no results of the nature of theorem 1.1, i.e. periodic solutions in a potential well. The more similar situations to the one considered in this paper are the following ones

- (a) Ω is a compact manifold without boundary
- (b) $\Omega = \mathbb{R}^n$ but U grows more than quadratically for $|x| + +\infty$ or, more precisely $0 < U(x) \le \theta U(x) \cdot x$ for x large

(notice that the above condition is the analogous of (L_3) when $\Omega = \mathbb{R}^n$).

In both cases (a) and (b) we have a result similar to heorem 1.1 (cf. $[B_2]$ for (a); $[R_4]$, [BF] or [G] for (b); also the case (b) has been considered in $[R_2]$, [BR] and [BCF] in the context of Hamiltonian systems).

What we want to remark here is the similarity of these three situations. In case (a), the existence of infinitely many periodic orbits can be proved by virtue of the compactness of Ω (provided that Ω satisfy some suitable geometric assumption as having the fundamental group finite). In (b) and in theorem 1.1, the lack compactness is replaced by the growth of U.

A last remark about the technique used to prove theorem 1.1. We have used variational arguments reducing our problem to the proof of existence of critical points of a functional defined on an open set in a Hilbert space. In proving the existence of critical points for functional in infinite dimensional manifold the well known condition (c) of Palais and Smale (P.S.) has been used. However in our situation (since we deal with a non-closed manifold) (P.S.) is not sufficient. For this reason we have used a variant of (P.S.),

which fit our case, obtaining an abstract theorem (theorem 2.3) which might have some interest in itself as a further step in understanding the critical point theory in infinite dimensional manifolds.

2. AN ABSTRACT THEOREM.

Let X be a Hilbert space with norm $f \circ f$ and scalar product $\langle \cdot , \cdot \rangle$ and let Λ be an open set in X (or more in general a Riemannian manifold embedded in X). $C^n(\Lambda, R)$ will denote the set of n-times Frechét differentiable functions from X to R.

If $f \in C^{n}(A,R)$, f^{*} will denote its Frechét derivative which can be identified, by virtue of $\langle \cdot, \cdot \rangle$, with a function from A to X.

Definition 2.1. A function $\rho: A + X$ is called a weight function for A if it satisfies the following assumptions:

- (i) ρ e c (A,R)
- (ii) $\rho(x) > 0$ for every $x \in \Lambda$
- (iii) $\lim_{x\to\partial A} \rho(x) = +\infty$ $\lim_{x\to\partial A} \frac{\rho(x)}{\rho(x)} = +\infty$ Definition 2.2. We say that a functional $J\in C^1(A,\mathbb{R})$ satisfies the weighted Palais-Smale condition (abbreviated W.P.S.) if there exists a weight function ρ such that given any sequence $x_n\in A$ the following happens:

(WPS 1) if $\rho(x_n)$ and $J(x_n)$ are bounded and $J^*(x_n) + 0$ then x_n has a subsequence converging to $\bar{x} \in A$

(WPS 2) if $J(x_n)$ is convergent and $\rho(x_n)++\!\!\!-\!\!\!-\!\!\!-$, then there exists $\nu>0$ such that

 $\|J^{\dagger}(x_n)\| > \nu \|\rho^{\dagger}(x_n)\|$ for n large enough.

Remarks. (I) We say that a functional satisfy the Palais-Smale assumption on a Hilbert (or Banach) manifold Λ if every sequence \mathbf{x}_n such that $J(\mathbf{x}_n)$ is bounded and $J^*(\mathbf{x}_n) + 0$ has a converging subsequence. Most results in critical point theory have been obtained using the (P.S.) assumption. However, as easy examples show (P.S.) is not sufficient to obtain existence results when Λ is an open set in a Hilbert space, or to be more precise, when Λ is not complete with respect to the Riemannian structure which we want to use.

(II) If \hat{A} is a closed Hilbert (or Banach) manifold then (P.S.) implies (W.P.S.) (it is enough to take $\rho \equiv 1$). Moreover if $\hat{A} = X$, choosing $\rho(x) = \log(1 + \|x\|^2)$, then

(W.P.S.) reduces to a generalization of (P.S.) introduced by G. Cerami [C] (cf. also [B.B.F.] and [B.C.F.]).

(III) If a functional J satisfy (P.S.) then the set

$$K_c = \{ \gamma \in \Lambda | J(\gamma) = c, J'(\gamma) = 0 \}$$

is compact. If J satisfies (W.P.S.) we can only conclude that

$$K_C \cap \{ \gamma \in \Lambda | \rho(\gamma) \leq M \}$$

is compact for every M > 0. Thus (W.P.S.) might be an useful tool for analyzing situations in which we do not expect to find a compact set of critical points at a given value c. (However if $\rho^*(x) \neq 0$ when $\rho(x)$ is large, then K_C is compact).

Definition 2.2. Let X be an Hilbert (or Banach) space. Let S be a closed set in

X, and let Q be an Hilbert manifold with boundary 8Q. We say that S and 8Q link if

- (a) S ∩ 3Q = \$
- (b) if $h: \overline{Q} + A$ is a continuous map such that h(u) = u for every $u \in \partial Q$, then $h(Q) \cap S = \phi$.

Theorem 2.3. Let Λ be a Riemannian manifold embedded in a Hilbert space X and let $J \in C^2(\Lambda, \mathbb{R})$. We suppose that

- (J₁) J satisfy (W.P.S.)
- (J₂) there exists a closed subset $S \subset \Lambda$ and an Hilbert manifold $Q \subset \overline{\Lambda}$ with boundary ∂Q , and two constants $0 < \alpha < \beta$ such that
 - (a) $J(\gamma) \le \beta$ for $\gamma \in Q$ and min $\lim J(\gamma) \le 0$
 - (b) $J(\gamma) > \alpha$ for every $\gamma \in S$
 - (c) S and 3Q link.

We set $H = \{h : \overline{Q} + \overline{A} | h(\gamma) = \gamma \text{ if } J(\gamma) \leq 0\}$ and

c = inf sup J ° h(γ)

Then c @ [a, ß] and it is either a critical value of J or an accumulation point of critical values of J.

Remarks. (I) Theorem 2.3 is a variant of similar results (see [B.B.F.] theorem 2.3, [B.R.] or $[R_3]$). The novelty lies in the fact that Λ might be an open set, therefore

(P.S.) is not sufficient to guarantee that c is a critical value of J. Therefore we have to require (W.P.S.). A consequence of this fact is that we do not know that c is a critical value of J; it might be an accumulation point of critical values of J (unless (P.S.) is also satisfied)

(II) The assumption $J \in C^2(\Lambda, \mathbb{R})$ is not necessary. It would be enough to assume $J \in C^1(\Lambda, \mathbb{R})$. With the latter assumption the proof of lemma 2.4 would be more technical. However if the reader is interested to prove theorem 2.3 under the less restrictive assumption, he has to "interpolate" between the proof of lemma 2.4 and theorem 1.3 in [B.B.F.]. Since in our application, it is sufficient to assume $J \in C^2(\Lambda, \mathbb{R})$, we did not bother to be as general as possible.

To prove theorem 2.3, we need the following lemma

Lemma 2.4. Let $J \in C^2(\Lambda, \mathbb{R})$ satisfy (W.P.S.). Suppose that c is not a critical value of J nor an accumulation point of critical values of J. Then there exist constants $\overline{\epsilon} > \epsilon > 0$ and a function $\eta : [0,1] \times \Lambda + \Lambda$ such that

- (a) $\eta(0,x) = x$ for every $x \in \Lambda$
- (b) $\eta(1,x) = x$ for every x such that $J(x) \notin [c \tilde{\epsilon}, c + \bar{\epsilon}]$ and every $t \in \mathbb{R}$
- (c) $\eta(1,\lambda_{c+\epsilon}) \subset \lambda_{c-\epsilon}$

where $\lambda_b = \{x \in \Lambda | J(x) \le b\}$. Moreover ϵ can be chosen arbitrarily small.

Proof. We set

$$S_{\varepsilon} = \{x \in \Lambda | c - \varepsilon \leq J(x) \leq c + \varepsilon\}$$

$$\Delta_{M} = \{x \in \Lambda | \rho(x) \leq M\}$$

We claim that there exists $\vec{\epsilon}$, \vec{M} and \vec{b} such that

(2.1)
$$||J'(x)|| > b||\rho'(x)|| \text{ for every } x \in S_{\overline{E}} - \Delta_{\overline{M}}.$$

In order to prove (2.1) we argue indirectly. Suppose that (2.1) does not hold. Then there exists a sequence \mathbf{x}_n such that

(a)
$$J(x_n) + c$$

(2.2) (b)
$$\rho(x_n) + +\infty$$

(c)
$$\|J'(x_n)\| \le b_n \|\rho'(x_n)\|$$
 with $b_n + 0$.

Then we have

$$0 < \nu \le \min \lim \frac{\|J^{+}(x_{n})\|}{\|\rho^{+}(x_{n})\|}$$
 (by (2.2)(a)(b) and (W.P.S.)(ii))
$$\le \min \lim b_{n} = 0$$
 by (2.2)(c)

This is a contradiction which proves (2.1). It is not restrictive to suppose that $\bar{\epsilon}$ is so small that $[c - \bar{\epsilon}, c + \bar{\epsilon}]$ does not contain critical values of J_I this is possible because we have supposed that c is not an accumulation point of critical values.

We claim that for every M, there exists $b_{M} > 0$ such that

(2.3)
$$\|J^{\dagger}(x)\| \ge b_{M}$$
 for every $x \in A_{M}$.

In fact if (2.3) does not hold there exists a sequence such that

(a)
$$J(x_n) \in [c - \overline{\epsilon}, c + \overline{\epsilon}]$$

(2.4) (b)
$$\rho(x_n) \le M$$

(c)
$$\|J^*(x_n)\| \le b_n$$
 for some sequence $b_n + 0$.

Then, by (WPS 1), it follows that x_n has a subsequence conveying to some limit \bar{x} . So we have

$$J^{\dagger}(\vec{x}) = 0$$
 and $J(\vec{x}) = \vec{c} \stackrel{\text{def}}{=} \lim_{n \to +\infty} J(x_n)$.

Thus $\bar{c} \in [c - \bar{\epsilon}, c + \bar{\epsilon}]$ is a critical value of J contradicting our choice of $\bar{\epsilon}$. Let ϕ : A + R be a Lipschitz continuous function such that

(2.4)
$$\phi(x) = \begin{cases} 1 & \text{if } x \in S_{\epsilon/2} \\ 0 & \text{if } x \notin S_{\epsilon} \end{cases}$$

and we set

(2.5)
$$V(x) = \begin{cases} \phi(x) \frac{J^{\dagger}(x)}{IJ^{\dagger}(x)I^{2}} & \text{for } x \in S_{\overline{\epsilon}} \\ 0 & \text{for } x \notin S_{\overline{\epsilon}} \end{cases}$$

By (2.1) and the definition of ϕ , V is well defined and locally Lipschitz continuous. We now consider the following initial value problem

By basic existence theorems for such equations, for each $x \in \Lambda$ there exists a unique solution $\eta(t,x)$ of (2.6) defined for $t \in (t^-(x),t^+(x))$, a maximal interval depending on x. We claim that $t^{\pm}(x) = \pm \infty$. Let us prove that

$$t^+(x) = +\infty$$
.

We argue indirectly and suppose that $t^{+}(x) < +\infty$.

First of all we can suppose that

(2.6')
$$\eta(t,x) \in S_{\bar{E}} \text{ for } t \in [0,t^+(x))$$

otherwise the conclusion follows directly from (2.5). If (2.6') does not hold we claim that

(2.6")
$$\rho(\eta(t)) \leq M \text{ for every } t \in [0,t^+(x))$$

where $M = M_1 + \frac{t^+(x)}{b}$ and $M_1 = \max\{\rho(0), \overline{M}\}$. If the above inequality does not hold then there exists t_1 , t_2 with $0 \le t_1 < t_2 < t^+(x)$ such that

$$M_1 \le \rho(n(t)) \le M$$
 for te[t₁,t₂]

and

(2.7)
$$\rho(\eta(t_1)) = M_1; \quad \rho(\eta(t_2)) = M_3$$

then, for $t \in [t_1, t_2]$

$$|\frac{d}{dt} \rho(\eta(t,x))| = |\langle \rho^{\dagger}(\eta(t,x)), V(\eta(t,x))\rangle| \quad \text{[by (2.6)]}$$

$$< \phi(\eta(t)) \frac{\|\rho^{\dagger}(\eta(t,x))\|}{\|J^{\dagger}(\eta(t,x))\|} \quad \text{[by (2.5)]}$$

$$< \frac{1}{h} \quad \text{[by (2.6^{\dagger}), (2.4^{\dagger}) and (2.1)]}$$

Then we have

$$M - M_1 = \rho(\eta(t_2, x)) - \rho(\eta(t_1, x)) \quad \text{[by (2.7)]}$$

$$\leq \int_{t_1}^{t_2} \left| \frac{d}{dt} \rho(\eta(t, x)) \right| dt$$

$$\leq (t_2 - t_1) \frac{1}{b} \quad \text{[by the above inequality]}$$

$$\leq \frac{t^+(x)}{b} = M - M_1 \quad \text{[by the definition of M]}$$

This is a contradiction. Therefore (2.6") is proved.

Then by (2.3), there exists $b_{M} > 0$ such that (2.7') $\|J^{1}(\eta(t,x))\| > b_{M}$ for $t \in [0,t^{+}(x))$

Now let t_n be a sequence such that $t_n + t^+(x)$. So we have

$$\|\eta(t_{n+k},x) - \eta(t_{n},x)\| = \|\int_{t_{n}}^{t_{n+k}} V(\eta(t,x))dt\| \quad [by (2.6)]$$

$$< \int_{t_{n}}^{t_{n+k}} \frac{dt}{\|J^{+}(\eta(t,x))\|} \quad [by (2.4) \text{ and } (2.5)]$$

$$< b_{M}^{-1}(t_{n+k} - t_{n}) \quad [by (2.7^{+})]$$

This implies that $\eta(t_n,x)$ is a Cauchy sequence converging some $x_0 \in \overline{\Lambda}$ as $t_n + t^+(x)$. Moreover $\rho(\overline{x}) = \lim_{n \to +\infty} \rho(\eta(x,t_n)) \le M$, therefore, by Definition (2.1)(iii), $\overline{x} \in \Lambda$. But the solution of (2.6) with initial condition \overline{x} furnishes a continuation of $\eta(t,x)$ contradicting the maximality of $t^+(x)$. Analogously we can prove that $t^-(x) = -\infty$. Therefore $\eta(t,x)$ is defined for every $t \in \mathbb{R}$. Since $\frac{d}{dt} J(\eta(t,x)) = -1$ if $\eta(t,x) \in S_{\overline{k}/2}$ by an easy standard argument the conclusion follows.

Proof of Theorem 2.3. By virtue of lemma 2.4, the proof of theorem 2.3 is almost a repetition of analogous proofs (cf. e.g. [B.R.], [R_3] or [B.F.]). We sketch it for completeness. By the first part of $(J_2)(a)$ and since the identity belong \overline{B} , $c \le \beta$. By the second part of $(J_2)(a)$ and $(J_2)(c)$, $h(0) \cap S \ne \phi$; then by $(J_2)(b)$, $c \ge \alpha$. Then c = 1

is well defined and is in $\{\alpha,\beta\}$. It remains to prove that c is a critical value of J or it is an accumulation point of critical values of J. Suppose that neither possibility holds. Then the assumptions of lemma 2.4 are satisfied. Choose $\bar{\epsilon} \in (0,\alpha]$, ϵ and η as in lemma 2.4. By the definition of c, there exists $\bar{h} \in \mathbb{R}$ such that

$$\sup_{x \in Q} \mathbf{J} \cdot \tilde{h}(x) \leq c + \varepsilon$$

By lemma (2.4)(c) and the above inequality we have

THE PARTY STANDING CERTIFIED AND STANDING MANY TOLD

(2.8)
$$\sup_{\mathbf{x} \in \Omega} \mathbf{y} \bullet \mathbf{h} = \mathbf{h}(\mathbf{x}) \leq \mathbf{c} - \mathbf{\epsilon}$$

By lemma (2.4)(b) and the choice of $\bar{\epsilon}$, $\eta \cdot \bar{h} \in H$; then by the definition of c

$$\sup_{x \in Q} J \cdot \eta \cdot \overline{h}(x) \ge c$$

The above inequality contradicts (2.8). Thus the theorem is proved.

3. PROOF OF THEOREM 1.1.

We set

(3.1)
$$\Lambda^{1}\Omega = \{ \gamma \in H^{1}(S^{1}, \mathbb{R}^{n}) | \gamma(t) \in \Omega \} \quad (S^{1} = [0,1]/\{0,1\})$$

where $H^1(S^1,\mathbb{R}^n)$ denotes the Sobolev space obtained by the closure of C^{∞} -functions (periodic of period 1) with respect to the norm

$$\|\gamma\| = \left[\int_{0}^{1} \{|\dot{\gamma}|^{2} + |\gamma|^{2}\} dt\right]^{1/2}$$

Since $H^1(S^1,\mathbb{R}^n)\subset C^0(S^1,\mathbb{R}^n)$, then the set $\Lambda^1\Omega$ is an open set in $H^1(\Omega,\mathbb{R}^n)$. The periodic solution of (1.2) are, at least formally, the critical value of the functional (3.2) $J(\gamma)=\int \left\{\frac{1}{2}a(\gamma)|\dot{\gamma}|^2-U(\gamma)\right\}dt$

However the functional (3.2) does not satisfy W.P.S. (nor the condition (J_2) of theorem 2.3) on the set (3.1). Therefore it is necessary to modify the functional (3.2) in a suitable way. Then we shall apply theorem 2.3 to the modified functional and finally we shall prove that the solutions of the modified functional are the solutions of our problem.

In order to carry out this program we start defining a function $h \in C^2(\overline{\Omega})$ with the following properties

$$(i) \ h(x) = d(x,\partial\Omega) \ if \qquad d(x,\partial\Omega) \leq d_0$$

$$(ii) \ h(x) \geq d_0 \qquad \text{whenever} \quad d(x,\partial\Omega) \geq d_0$$

$$(iii) \ \nabla h(x) \leq 1 \qquad \text{for every } x \in \overline{\Omega}$$

$$(iv) \ h(x) \leq 1 \qquad \text{for every } x \in \overline{\Omega}$$

where d_0 is a constant sufficiently small. Such a function h exists since Ω is assumed to have a C^2 -boundary. Also we set

(3.4)
$$h_0 = \sup_{\substack{x \in \Omega \\ \delta x \in \mathbb{R}}} \frac{d^2 h(x) [\delta x]^2}{|\delta x|^2}$$

where d^2h denotes the second differential of h. Moreover we set $(3.5) \qquad \qquad \nu(x) = -\nabla h(x) \text{ so that } \nu(x) \in C^1(\Omega, \mathbb{R}^n) \text{ and } |\nu(x)| \leq 1 \text{ .}$ Now let $\phi, \chi \in C^\infty(\mathbb{R})$ be two functions such that

$$\phi(t) = t \qquad \text{for } t > 1$$

$$\phi(t) = \frac{1}{2} \qquad \text{for } t < \frac{1}{2}$$

$$0 < \phi^{\dagger}(t)t < \phi(t) \quad \text{for } t \in \mathbb{R}$$

$$\chi(t) = 0 \qquad \text{for } t < 1$$

$$\chi(t) = 1 \qquad \text{for } t > 2$$

$$\chi^{\dagger}(t) > 0 \qquad \text{for } t \in \mathbb{R}$$

and set

$$a_{\lambda}(x) = \frac{1}{\lambda} \phi(\lambda a(x))$$

$$U_{\lambda,N}(x) = \frac{1}{N^2} \left\{ \chi(\lambda h(x))U(x) + \left[1 - \chi(\lambda h(x))\right] \frac{M_{\lambda}}{h(x)^2} \right\}$$

where $M_{\lambda} = \sup\{U(x) \mid x \in h^{-1}([\frac{1}{\lambda}, \frac{2}{\lambda}])\}$. Clearly a_{λ} and $U_{\lambda,N}$ are C^2 -functions and (3.6) $a_{\lambda}(x) > \frac{1}{2\lambda}$ for every $x \in \Omega$

Our modified functional will be

$$J_{\lambda,N}(\gamma) = \int_0^1 \left\{ \frac{1}{2} a_{\lambda}(\gamma) |\dot{\gamma}|^2 - U_{\lambda,N}(\gamma) \right\} dt$$

It is easy to check that $J_{\lambda,N}(\gamma) \in C^2(\Lambda^{1}\Omega,R)$ and that

$$J_{\lambda,N}^{*}(\gamma) \left[\delta \gamma\right] = \int_{0}^{1} \left\{ a_{\lambda}(\gamma) \dot{\gamma} + \delta \dot{\gamma} + \frac{1}{2} \left(\nabla a_{\lambda}(\gamma) + \delta \gamma \right) \left| \dot{\gamma} \right|^{2} - \nabla u_{\lambda,\gamma}(\gamma) + \delta \gamma \right\} dt$$

for
$$\gamma \in \Lambda^1 \Omega$$
 and $\delta \gamma \in H^1(S^1, \mathbb{R}^n)$

Now we want to apply theorem 2.3 to the functional $J_{\lambda,N}$. In order to do this some lemmas are necessary.

Lemma 3.1. (a) there exists a constant $b = b(\lambda, N)$ such that

$$b\left(\frac{1}{h(x)^{2}}\right) \leq v_{\lambda,N}(x) \leq b\left(\frac{1}{h(x)^{2}} + 1\right)$$

(b) there are positive constants β and K_1 (which may depend on λ and N) such that

$$\nabla u_{\lambda,N}(x) \cdot \nu(x) > \beta \frac{1}{h(x)^3} - \kappa_1$$

- (c) for every M > 0 there are constants a(M) and $\overline{\lambda}$ (M) such that $U_{\lambda,N}(x) \le \frac{1}{M} \nabla U_{\lambda,N}(x) \cdot \nu(x) + a(M) \quad \text{for every } x \in \Omega \quad \text{and every } \lambda > \overline{\lambda}(M)$
- (d) there exists a function $\lambda + \theta(\lambda)$ such that
 - (i) $\lim_{\lambda \to \infty} \theta(\lambda) = +\infty$
 - (ii) for every $u \in \Omega$ such that $U_{\lambda,N}(x) < \frac{1}{N^2} \theta(\lambda)$, we have

 $U_{\lambda,N}(x) = \frac{1}{N^2}U(x)$ and $a_{\lambda}(x) = a(x)$

(e) there exists a constants X such that

$$\nabla a_{\lambda}(x) \cdot v(x) \leq K a_{\lambda}(x)$$
 for every $x \in \Omega$ and every $\lambda > 0$

Proof. (a) and (b) follows by the fact that for x sufficiently close to $\partial \Omega$, $U_{\lambda,N}(x) = \frac{M_{\lambda}}{N^2} \cdot \frac{1}{h(x)^2}$ (remember that for x sufficiently close to $\partial \Omega$, $|\nabla h(x)| = 1$).

Let us prove (c). Since $v(x) = -\nabla h(x)$ we have:

$$(3.6a) \qquad \nabla U_{\lambda,N}(x) \circ \nu(x) = \frac{1}{N^2} \left\{ \chi(\lambda h(x)) \nabla U(x) \circ \nu(x) + \left[1 - \chi(\lambda h(x))\right] \frac{\left|\nu(x)\right|^2}{h^3(x)} \right\} \\ + \lambda \chi^* (\lambda h(x)) \left[\frac{M_{\lambda}}{h(x)^2} - U(x)\right] |\nu(x)|^2 \right\}$$

If $\chi'(\lambda h(x)) \neq 0$, then $x \in h^{-1}([\frac{1}{\lambda}, \frac{2}{\lambda}])$. Thus for such values of x, by (3.3)(iv) and the definition of M_{λ} we have

$$\frac{M_{\lambda}}{h(x)^2} - U(x) > M_{\lambda} - U(x) > 0$$

Thus, since $\chi^1(t) \ge 0$ for every $t \in \mathbb{R}$,

(3.6b)
$$\chi^*(\lambda h(x)) \left[\frac{M_{\lambda}}{h(x)^2} - U(x) \right] > 0 \text{ for every } x \in \Omega$$

By (L_3) and easy computations, for every M > 0 there exists a_0 such that

(3.6c) $\nabla U(x) \cdot v(x) > MU(x) - a_0$ for every $x \in \Omega$

Moreover, for x sufficiently close to $\partial\Omega$

$$\frac{|v(x)|^2}{h(x)^3} > \frac{M}{h(x)^2}$$

Then there exists $\bar{\lambda}(M)$ such that, for $\lambda > \bar{\lambda}(M)$

$$[1 - \chi(\lambda h(x))] \frac{|\nu(x)|^2}{h(x)^3} > [1 - \chi(\lambda h(x))] \frac{H}{h(x)^2}$$

So by (3.6a), (3.6b), (3.6c) and the above inequality we get

$$\nabla U_{\lambda,N}(x) \circ V(x) > \frac{1}{N^2} \left\{ \chi(\lambda h(x)) M U(x) - a_0 + \left[1 - \chi(\lambda h(x))\right] \frac{M M_{\lambda}}{h(x)^2} \right\} > M U_{\lambda,N}(x) - a_0$$

From the above inequality (c) follows. Now let us prove (d). We set

$$\Omega_{\lambda} = \{x \in \Omega | \lambda h(x) > 2 \text{ and } \lambda a(x) > 1\}$$

and

$$\theta(\lambda) = \inf \{ \chi(\lambda h(x)) U(x) + [1 - \chi(\lambda h(x))] \frac{M_{\lambda}}{h(x)^{2}} \mid x \in \Omega - \Omega_{\lambda} \}$$

by (3.3), (L₅) and (L₂), $\theta(\lambda) + +\infty$ for $\lambda + +\infty$. Moreover, if $U_{\lambda,N}(x) < \frac{\theta(\lambda)}{N^2}$, by the definition of $\theta(\lambda)$, $x \in \Omega_{\lambda}$. Then $\lambda h(x) > 2$ and $\lambda a(x) > 1$. Therefore $\chi(\lambda h(x)) = 1$ and $\frac{1}{\lambda} \phi(\lambda a(x)) = a(x)$. This proves (d). In order to prove (e), we set

$$\Gamma = \{x \in \partial\Omega | a(x) = 0\}.$$

Since a(x) > 0 for $x \in \Omega$ it follows that $\nabla a(x) \cdot v(x) < 0$ for every $x \in \Gamma$. By virtue of (L_6) and the compactness of Γ , there exists a constant $\delta > 0$ such that

(3.6d) $\nabla a(x) \cdot v(x) \leq -\delta$ for every $x \in \Gamma$.

Let

$$B = \{x \in \Omega | \nabla a(x) \cdot v(x) < 0\}$$

By (3.6d), B is an open neighborhood of Γ relative to $\vec{\Omega}$. Then, since $\vec{\Omega}$ - B is compact, by (L₅), there exists a constant c_1 such that

 $a(x) > c_1$ for every $x \in \overline{\Omega} - B$.

Using again the compactness of $\bar{\Omega}$ - B, there exists a constant c_2 such that

 $\nabla a(x) \cdot v(x) \le c_2$ for every $x \in \overline{\Omega} - B$.

So, choosing $K = c_2/c_1$, it follows that

(3.6e)
$$Va(x) \cdot v(x) \leq Ka(x)$$
 for every $x \in \Omega$

Then we have

$$\begin{aligned} & \nabla a_{\lambda}(x) \circ v(x) = \phi^*(\lambda x) \nabla a(x) \circ v(x) \\ & > K \phi^*(\lambda x) a(x) & \text{by (3.5e)} \\ & > K \frac{1}{\lambda} \phi(\lambda x) = K a_{\lambda}(x) & \text{by the definition of } \phi & \text{and } a_{\lambda} \end{aligned} . \quad \Box$$

In order to apply theorem 2.3 to the functional $J_{\lambda,N}$ it is necessary to choose an appropriate weight function; we make the following choice

(3.7)
$$\rho(\gamma) = \left[\int_{0}^{1} \frac{1}{h(\gamma)^{2}} dt \right]^{1/2}$$

Lemma 3.2. The function ρ defined by (3.7) satisfies the assumptions of definition 2.1. Proof. (i) and (ii) are trivial. Let us prove (iii). Let $\gamma_k \in \Lambda^1\Omega$ be a sequence approaching $\partial \Lambda^1\Omega$ and let t_k be such that $\operatorname{dist}(\gamma_k(t_k),\partial\Omega) \leq \operatorname{dist}(\gamma_k(t),\partial\Omega)$ for every $t \in (0,1)$. We want to prove that $\rho(\gamma_k) + +\infty$. Since ρ is invariant for "time translations", we can suppose that $t_k = 0$ for every k.

By the Schwartz inequality we have

$$|\gamma_k(t) - \gamma_k(0)| < \int\limits_0^t |\mathring{\gamma}_k(t)| < t^{1/2} [\int\limits_0^t |\mathring{\gamma}_k(t)|^2]^{1/2} < \|\gamma_k\| \cdot t^{1/2}$$

Then, by (3.3)(iii),

(3.8)
$$|h(\gamma_k(\epsilon)) - h(\gamma_k(0))| \leq \max_{x \in \Omega} |\nabla h(x)| \cdot |\gamma_k(\epsilon) - \gamma_k(0)| \leq \|\gamma_k\|\epsilon^{1/2}$$

If we set

$$m(\gamma_k) = h(\gamma_k(0))$$

by (3.8) we get

$$h(\gamma_k(t)) \leq m(\gamma_k) + \|\gamma\|t^{1/2}.$$

We can assume that $\|\gamma_k\| > \alpha > 0$ for k large and some positive constant α . Then we

have

$$\frac{1}{h(\gamma(t))^{2}} > \frac{1}{(m(\gamma) + \|\gamma\|t^{1/2})^{2}} > \frac{1}{2} \frac{1}{m(\gamma)^{2} + \|\gamma\|^{2}t}$$

Sa

$$p(\gamma_k)^2 = \int_0^1 \frac{1}{h(\gamma(t))^2} dt > \frac{1}{2} \int_0^1 \frac{dt}{m(\gamma)^2 + \|\gamma\|^2 t} = \frac{1}{\|\gamma_k\|^2} \log(1 + \frac{\|\gamma_k\|^2}{m(\gamma_k)^2})$$

From the above inequality and since $\|\gamma_k\| > \alpha > 0$ and $m(\gamma_k) + 0$ for $k + + \infty$ the conclusion follows.

Lemma 3.3. For every N > 1 and $\lambda > 0$, the functional $J_{\lambda,N}$ satisfy W.P.S.

Proof. To simplify the notation, in this proof we shall write $J_{\lambda}U$ and a instead of $J_{\lambda,N}$, $U_{\lambda,N}$ and a_{λ} . Let us start to prove WPS 1. In the following $a_{1},a_{2},...$ will denote suitable positive constants. Since $\rho(\gamma_{n})$ is bounded, then by lemma 3.2, dist $(\gamma_{n},\partial A^{1}\Omega) > a_{1} > 0$. So dist $(\gamma_{n},\partial A^{1}\Omega) > a_{1} > 0$ and this implies that dist $(\gamma_{n}(t),\partial\Omega) > a_{1} > 0$ for every $t \in [0,1]$.

Since $J(\gamma_n)$ is bounded it follows that

$$\int \frac{1}{2} a(\gamma_n) \dot{\gamma}_n^2 dt \quad \text{is bounded.}$$

Then $\|\gamma\|_{H^{\frac{1}{2}}}$ is bounded, therefore (may be taking a subsequence) we have that (3.10) $\gamma_n + \tilde{\gamma}$ weakly in $H^1(S^1, \mathbb{R}^n)$ and uniformly.

We have to prove that $\gamma_n + \bar{\gamma}$ strongly in $H^1(S^1, \mathbb{R}^n)$. Since we suppose that $J^1(\gamma_n) + 0$, we have that

$$(3.12) \qquad \int \nabla u(\gamma_n) \delta \gamma < \| \nabla u(\gamma_n) \|_{L^{\infty}} \int \delta \gamma < a_2 \| \delta \gamma \|_{L^{\infty}}$$

Also, using (3.10), we have

(3.13)
$$\frac{1}{2} \int \nabla a(\gamma_n) \cdot \delta \gamma |\dot{\gamma}_n|^2 \leq \frac{1}{2} \| \nabla a(\gamma_n) \|_{L^{\infty}} \| \delta \gamma \|_{L^{\infty}} \| \gamma_n \|_{H^{1}}^2 \leq a_3 \| \delta \gamma \|_{L^{\infty}}$$

By (3.11), (3.12) and (3.13) it follows that

$$\int a(\gamma_n) \dot{\gamma}_n \delta \dot{\gamma} = \varepsilon_n \delta \dot{\gamma} \delta \dot{\gamma} + (a_2 + a_3) \delta \dot{\gamma} \delta \dot{\gamma}$$

for every $\delta \gamma \in H^1(S^2, \mathbb{R}^n)$. In particular, taking $\delta \gamma = \gamma_n - \overline{\gamma}$ we get

(3.14)
$$\int a(\gamma_n)\dot{\gamma}_n(\dot{\gamma}_n - \dot{\bar{\gamma}}) = \varepsilon_n \|\gamma_n - \bar{\gamma}\| + o(1)$$

since $\|\gamma_n - \overline{\gamma}\|_{\infty} + 0$ for $n + +\infty$. So by (3.6) and (3.14) we have

$$\begin{split} \frac{1}{2\lambda} \, \, & \| \gamma_n - \bar{\gamma} \|^2 \, \leq \, \frac{1}{2\lambda} \, \int \, |\dot{\gamma} - \dot{\gamma}_n|^2 \, + \, o(1) \, \leq \, \int \, a(\gamma_n) |\dot{\gamma}_n - \dot{\bar{\gamma}}|^2 \, + \, o(1) \, \\ \\ &= \, \int \, a(\gamma_n) \dot{\gamma}_n (\dot{\gamma}_n - \dot{\bar{\gamma}}) \, - \, \int \, a(\gamma_n) \dot{\bar{\gamma}} (\dot{\gamma}_n - \bar{\gamma}) \, + \, o(1) \, \\ \\ &\leq \, \epsilon_n \| \gamma_n - \bar{\gamma} \| \, + \, \| a(\gamma_n) \|_{\bar{\gamma}_n} \, \int \, \dot{\bar{\gamma}} (\dot{\gamma}_n - \dot{\bar{\gamma}}) \, + \, o(1) \, = \, \epsilon_n \| \gamma_n - \bar{\gamma} \| \, + \, o(1) \, \end{split}$$

from which the conclusion follows. Now we shall prove W.P.S.(ii). In the following b_1, b_2, \ldots will denote suitable positive constants. Now let γ_n be a sequence such that

(3.15) (a)
$$J(\gamma_n)$$
 is convergent

(b) $\rho(\gamma_n) + +\infty$

Then we have

$$\frac{1}{2\lambda} \int |\dot{\uparrow}_n|^2 \le \int a(\gamma_n) |\dot{\uparrow}_n|^2 \qquad \text{(by (3.6))}$$

$$\le \int U(\gamma_n) + b_1 \qquad \text{(by (3.15)(b))}$$

$$\le b_2 \int \frac{1}{h(\gamma_n)^2} + b_3 \qquad \text{(by lemma 3.1(a))}$$

$$= b_2 \rho(\gamma_n)^2 + b_3 \qquad \text{(by (3.7))}$$

We now set

$$\delta \gamma_n(t) = \nu(\gamma_n(t)) = -\nabla h(\gamma_n(t))$$

Thus by e H1(s1, H1) and

(3.17)
$$\|\delta\gamma_n\|^2 = \int |d^2h(\gamma_n)(\dot{\gamma}_n)|^2 + |\nabla h(\gamma_n)|^2 dt \le$$

$$\le b_5 \int |\dot{\gamma}_n|^2 + b_6 \qquad (by (3.3)(iii) and (3.4))$$

$$\le b_5 \rho(\gamma_n)^2 + b_6 \qquad (by (3.16))$$

Then by the above formula we have

(3.18)
$$||\delta\gamma_n|| \leq b_{\gamma\rho}(\gamma_n) + b_{\beta}$$

We have

$$\begin{split} & \| J^{*}(\gamma_{n}) \| \| (b_{7}\rho(\gamma_{n}) + b_{8}) > \| J^{*}(\gamma_{n}) \| \| \delta \gamma_{n} \| \qquad \text{(by (3.18))} \\ & > -J^{*}(\gamma_{n}) \{ \delta \gamma_{n} \} \\ & = \int_{0}^{1} \| \nabla U(\gamma_{n}) \cdot \delta \gamma_{n} - a(\gamma_{n}) \dot{\gamma}_{n} \delta_{\dot{\gamma}_{n}} - \frac{1}{2} \| \nabla a(\gamma_{n}) \cdot \delta \gamma_{n} \| \dot{\gamma}_{n} \|^{2} \\ & \qquad \qquad \text{(by the definition of } J^{*}) \\ & = \int_{0}^{1} \| \nabla U(\gamma_{n}) \cdot \nu(\gamma_{n}) - a(\gamma_{n}) d^{2}h \| \dot{\gamma}_{1} \|^{2} - \frac{1}{2} \| \nabla a(\gamma_{n}) \cdot \nu(\gamma_{n}) \| \dot{\gamma}_{n} \|^{2} \\ & \qquad \qquad \text{(by the definition of } \delta \gamma_{n}) \\ & > \int_{0}^{1} \| \nabla U(\gamma_{n}) \cdot \nu(\gamma_{n}) - \| a(\gamma_{n}) \|_{L^{\infty}} \| d^{2}h(\gamma_{n}) \| \cdot \|_{L^{\infty}} \int \| \dot{\gamma}_{n} \|^{2} dt \\ & \qquad \qquad - \frac{1}{2} \| \nabla a(\gamma_{n}) \|_{L^{\infty}} \| \nu(\gamma_{n}) \|_{L^{\infty}} \int \| \dot{\gamma}_{n} \|^{2} dt \\ & > b_{9} \int \frac{1}{h(\gamma_{n})^{3}} - b_{10} \int \| \dot{\gamma}_{n} \|^{2} - b_{10}^{*} \qquad \text{(by lemma 3.1)(b), (3.5) and (3.4))} \\ & > b_{9} \int \frac{1}{h(\gamma_{n})^{3}} - b_{11} \rho(\gamma_{n})^{2} - b_{12} \qquad \text{(by (3.16))} \end{split}$$

Next we shall compute $\{\rho^*(\gamma_n)\}$. We have

$$\rho^*(\gamma)[\delta\gamma] = -\left(\int \frac{1}{h(\gamma)^2} dt\right)^{-1/2} \int \frac{\nabla h(\gamma) \cdot \delta \gamma}{h(\gamma)^3} dt \quad \text{for } \gamma \in A^1\Omega \quad \text{and} \quad \delta \gamma \in H^1(S^1, \mathbb{R}^n)$$

then

$$\begin{split} \| \rho^*(\gamma) \| &= \sup_{\| \delta \gamma \| \neq 0} \frac{\rho^*(\gamma) \{ \delta \gamma \}}{\| \delta \gamma \|} = \frac{1}{\rho(\gamma)} \sup_{\| \delta \gamma \| \neq 0} \frac{1}{\| \delta \gamma \|} \int \frac{\nabla h(\gamma) \delta \gamma}{h(\gamma)^3} \, dt < \\ &< \frac{1}{\rho(\gamma)} \sup_{\| \delta \gamma \| \neq 0} \frac{L}{\| \delta \gamma \|} \int \frac{|\nabla h(\gamma)|}{h(\gamma)^3} \, dt < \frac{1}{\rho(\gamma)} \int \frac{|\nabla h(\gamma)|}{h(\gamma)^3} \, dt \; . \end{split}$$

By the Hölder inequality we have

$$\int_{0}^{1} \frac{1}{h(\gamma)^{2}} \le \left[\int \frac{1}{h(\gamma)^{3}} \right]^{2/3}$$

then

$$\int \frac{1}{h(\gamma)^3} > \left[\int \frac{1}{h(\gamma)^2} dt \right]^{3/2} = \rho(\gamma)^3$$

By the above inequality and (3.19) we get

$$\|\mathbf{J}_{\lambda}^{*}(\gamma_{n})\|(\mathbf{b}_{7}\rho(\gamma_{n}) + \mathbf{b}_{8}) \geq \frac{1}{2} \mathbf{b}_{9} \int \frac{1}{\mathbf{h}(\gamma)^{3}} + \frac{1}{2} \mathbf{b}_{9}\rho(\gamma_{n})^{3} - \mathbf{b}_{11}\rho(\gamma_{n})^{2} - \mathbf{b}_{12}$$

Now, since $p(\gamma_n) + +\infty$, for n large enough we have

$$\| J_{\lambda}^*(\gamma_n) \| > \frac{\mathbf{b}_{13}}{\rho(\gamma_n)} \int \frac{1}{\mathbf{h}(\gamma_n)^3}$$

Since $|\nabla h| \le 1$ (by (3.3)(iii)), the above inequality and (3.20) imply that

$$IJ_{\lambda}^{*}(\gamma_{n})I > b_{13}I\rho^{*}(\gamma_{n})I$$

and this proves W.P.S.(ii).

To simplify the notation we shall suppose that

Now let

$$V = \{ y \in H^1(S^1, \mathbb{R}^n) | y \text{ is a constant} \}$$

and let v^1 its orthogonal complement in $H^1(S^1,\mathbb{R}^n)$. We set

(3.22)
$$Q = [\forall \times \{r \in \sin 2\pi t | r > 0\}] \cap \Lambda^1 \Omega, e \in \mathbb{R}^n, |e| = 1.$$

Let R be a constant small enough in order that the ball of center 0 and radius R is contained in Ω . Then there exists an integer number N_{Ω} such that

 $\frac{1}{N}U(x) \le \frac{R^2}{8}$ for every $x \in B_R(0)$ and every $N > N_0$

By the above inequality we get that

(3.23) $U_{\lambda,N}(x) < \frac{R^2}{8}$ for every $x \in B_R(0)$ and every $N > N_0$ and $\lambda > \lambda_0$ where λ_0 is big enough in order that $U_{\lambda,N}(x) = \frac{U(x)}{N}$ for every $\lambda > \lambda_0$ and every $x \in B_R(0)$. Observe that

(2.23') if $U(x) = o(|x|^2)$ then we can choose $N_0 = 1$

provided that A is small enough

Now we set

(3.24)
$$S = \{ \gamma \in V^{\perp} | \| \gamma \| = R \}$$

We have the following lemma

Lemma 3.4. For every $\lambda > \lambda_0$ and $N > N_0$, $J_{\lambda,N}$ satisfy the assumptions (J_2) of theorem 2.3 where S and Q are defined by (3.22) and (3.24) respectively and α and β are constants which depend only on Ω . (but not on U, λ and N).

<u>Proof.</u> (a) If $\gamma \in Q$ then $\gamma(t) = y_1 + y_2 e \sin(2\pi t)$ with $y_1 \in \mathbb{R}^n$ and $y_2 \in \mathbb{R}$. Since $Q \subseteq \Lambda^1 Q$ then

$$y_1 + y_2 e \sin(2\pi t) \in \Omega$$
 for every $t \in [0,1]$

Therefore

The property of

(3.25) $|y_1| < dt$ $|y_2| < 2d$ where $d = \max_{x \in \partial \Omega} dist(x, \partial \Omega)$

Thus, by (3.21)

 $J_{\lambda,N}(\gamma) \leq \int \frac{1}{2} |y_2|^2 [2\pi \cos(2\pi t)]^2 dt \leq 8\pi^2 d^2 \frac{\deg f}{\delta} \beta \quad \text{for every } \gamma \in Q.$

Also β depend only on d i.e. on the geometry of Ω . Now let us prove that

(3.26) $\min_{\gamma + 30} \lim_{\gamma \to 30} J(\gamma) \leq 0$

We have

 $ag \subseteq (v \cap \Lambda^1 \Omega) \cup (g \cap a\Lambda^1 \Omega)$

If $\gamma \in V \cap \Lambda^1\Omega$ we have

 $J_{\lambda,N}(\gamma) = \int -U_{\lambda,N}(\gamma) dt \le 0$ (by (3.24) and the definition of V)

If $\gamma \in Q \cap \Lambda\Omega$ we have

$$J_{\lambda,N}(\gamma) = \int \left\{ \frac{1}{2} \left[y_2 \right]^2 (2\pi \cos 2\pi t)^2 - U_{\lambda,N}(\gamma) \right\} dt \le$$

$$\leq 8\pi^2 d^2 - b \int \frac{1}{h(\gamma)^2} + b \quad \text{(by lemma (3.1)(b))}$$

$$\leq \kappa - b\rho(\gamma)^2 \quad \text{(with } K = 8\pi d_1^2 + b)$$

Then (3.26) follows by the fact that $\lim_{\gamma \to 0\Lambda} \rho(\gamma) = +\infty$ (cf. lemma 3.2). Now let us prove that assumption $\{J_2\}$ (b) of theorem 2.3 holds. If $\gamma \in S$ then $\|\gamma\| = R$ and $\|\gamma\| \leq R$ for every $t \in [0,1]$. Then, for $\lambda > \lambda_0$ and $N > N_0$, by (3.23) we have

(3.27)
$$U_{\lambda,N}(\gamma(t)) \le \frac{R^2}{8}$$
 for every $t \in [0,1]$ and every $\gamma \in S$.

Moreover for $\gamma \in S$, by the Poincaré inequality $\int |\gamma|^2 \le \int |\dot{\gamma}|^2 \tau$ then

$$\int \frac{1}{2} |\dot{\gamma}|^2 > \frac{1}{4} \int |\dot{\gamma}|^2 + |\dot{\gamma}|^2 = \frac{1}{4} |\dot{\gamma}|^2 = \frac{1}{4} |\dot{\gamma}|^2 = \frac{1}{4} |\dot{\gamma}|^2 \text{ for } \dot{\gamma} \in S.$$

Thus by the above inequality and (3.27) we get

$$J_{\lambda,N}(\gamma) = \int \left[\frac{1}{2} |\hat{\gamma}|^2 - U_{\lambda,N}(\gamma(t)) \right] dt > \frac{1}{4} R^2 - \frac{1}{8} R^2 = \frac{1}{8} R^2 \frac{dgf}{dt} \alpha \text{ for every } \gamma \in S$$

This proves assumption (b) of theorem 2.3 with α depending only on R, i.e. on the geometry of Ω . The fact that S and $\partial\Omega$ link, is proved in proposition 2.2 of [B.B.F.]. Actually there Ω is defined in a slightly different way, but this fact does not affect the proof.

Finally we are able to find solutions of the modified problem. Lemma 3.5. For every $N > N_0$ and $\lambda > \lambda^* > \lambda_0$ (where λ^* is a suitable constant) there exists $\gamma_{\lambda,N} \in C^2(S^2,\Omega)$ such that

(a) $\alpha \in J_{\lambda,N}(\gamma_{\lambda,N}) \in \beta$ where α and β depend only on $\Omega.$

(b)
$$a_{\lambda}(\gamma_{\lambda,N})\gamma_{\lambda,N} = \frac{1}{2} |\gamma_{\lambda,N}|^2 \nabla a_{\lambda}(\gamma_{\lambda,N}) - (\nabla a_{\lambda}(\gamma_{\lambda,N}) \cdot \gamma_{\lambda,N})\gamma_{\lambda,N} - \nabla u_{\lambda,N}(\gamma_{\lambda,N})$$

(c) $\alpha \leqslant \frac{1}{2} a_{\lambda}(\gamma_{\lambda,N}(t)) |\dot{\gamma}_{\lambda,N}(t)|^2 + U_{\lambda,N}(\gamma_{\lambda,N}(t)) \stackrel{\text{def}}{=} E_{\lambda,N} \leqslant \sigma$ for every $t \in (0,1)$ where σ is independent of λ and N.

<u>Proof.</u> By lemma 3.3 and lemma 3.4 the functional $J_{\lambda,N}$ satisfies the assumptions of theorem 2.3. Then there exists $\gamma = \gamma_{\lambda,N} \in \Lambda^1 \Omega$ such that

(3.28)
$$J'(\gamma)[\delta\gamma] = 0 \text{ for every } \delta\gamma \in H^1(s^1, \mathbb{R}^n)$$

and

(3.29)
$$J(\gamma) = c_{\lambda,N} \text{ with } \alpha \leq c_{\lambda,N} \leq \beta$$

The above equation proves (a). Moreover by (3.28) it follows that $\gamma_{\lambda,N}(t)$ satisfies the equation (b) in a weak sense. By standard regularity arguments it follows that γ is of class C^2 . Now let us prove (c). It is easy to check that

$$(3.30) \qquad \frac{1}{2} a_{\lambda}(\gamma(t)) |\dot{\gamma}(t)|^2 + U_{\lambda,N}(\gamma(t))$$

is an integral of the equation (b) (in fact it is just the energy). Therefore it is independent of t; we shall call $E_{\lambda,N}$ its value. Integrating (3.30) between 0 and 1 we get

(3.31)
$$E_{\lambda,N} = \int \left\{ \frac{1}{2} a_{\lambda}(\gamma) |\dot{\gamma}|^2 + U_{\lambda,N}(\gamma) \right\} dt$$

Writing (3.29) explicitely we have

(3.32)
$$\alpha \leqslant \int \left\{ \frac{1}{2} a_{\lambda}(\gamma) |\dot{\gamma}|^2 - \upsilon_{\lambda,N}(\gamma) \right\} dt \leqslant \beta$$

By (3.31) and (3.32) we get

(3.33)
$$\alpha \leq E_{\lambda,N} \leq 2 \int U_{\lambda,N}(\gamma) dt + \beta$$

The above formula gives the first of the inequalities (b). In order to get the second one more work is necessary (and it will be necessary, for the first time, to use the assumption (L₃) which has been used to prove lemma 3.1(c)). Writing (3.28) explicitely with $\delta \gamma = \nu(\gamma) = -\nabla h(\gamma)$ we get

(3.34)
$$\int \left\{ a_{\lambda}(\gamma) d^{2}h[\dot{\gamma}]^{2} + \frac{1}{2} \nabla a(\gamma) \cdot v(\gamma) |\dot{\gamma}|^{2} - \nabla u(\gamma) \cdot v(\gamma) \right\} dt = 0$$

Now take $M = 4h_0 + 2K$. Then, for $\lambda > \overline{\lambda}(M)$, we have

$$\int U_{\lambda,N}(\gamma(t))dt < \frac{1}{M} \int \nabla U_{\lambda,N}(\gamma) \cdot \nu(\gamma)dt + a(M) \quad \text{(by lemma 3.1(c))}$$

$$= \frac{1}{M} \int \left\{ a_{\lambda}(\gamma)d^{2}h[\mathring{\gamma}]^{2} + \frac{1}{2} \nabla a_{\lambda}(\gamma) \cdot \nu(\gamma)|\mathring{\gamma}|^{2} \right\}dt + a(M) \quad \text{(by (3.34)}$$

$$< \frac{h_{0}}{M} \int a_{\lambda}(\gamma)|\mathring{\gamma}|^{2}dt + \frac{K}{2M} \int a_{\lambda}(\gamma)|\mathring{\gamma}|^{2}dt + a(M) \quad \text{(by (3.4) and lemma 3.1(e))}$$

$$= \frac{1}{M} (2h_0 + K) \left[\frac{1}{2} \int a_{\lambda}(\gamma) |\dot{\gamma}|^2 dt \right] + a(M)$$

$$\leq \frac{1}{2} \left[\int U_{\lambda,N}(\gamma) dt + \beta \right] + a(M) \quad \text{(by our choice of } M \text{ and (3.23)} \text{)}$$

Then we get

$$\frac{1}{2}\int U_{\lambda_{\alpha}N}(\gamma)dt \leq \frac{1}{2}\beta + \alpha(M)$$

By the above inequality and (3.33) the last inequality (c) holds with $\sigma = 3\beta + 2a(M)$ and $\lambda^+ = \max(\lambda(M), \lambda_0)$.

Finally we can prove theorem 1.1

<u>Proof of Theorem 1.1.</u> For any $N > N_0$ choose $\lambda(N) > \lambda^*$ large enough such that

$$\frac{\theta(\lambda(N))}{N^2} \geq \sigma$$

where $\theta(\lambda)$ is defined in lemma 3.1(d). Then setting $\widetilde{\gamma}_N(t) = \gamma_{\lambda(N),N}(t)$, by lemma 3.5 (c) we have

$$U_{\lambda(N),N}(\widetilde{\gamma}_N(t)) \le \sigma \le \frac{\theta(\lambda(N))}{N^2}$$
 for every $t \in [0,1]$

Thus by lemma (3.1)(d), we have that

(3.36)
$$a_{\lambda(N)}(\widetilde{\gamma}_{N}(t)) = a(\widetilde{\gamma}_{N}(t))$$

$$U_{\lambda(N),N}(\widetilde{\gamma}_{N}(t)) = \frac{1}{n^{2}}U(\widetilde{\gamma}(t)) \text{ for every } t \in [0,1]$$

By the above identity we have that

$$J_{\lambda,N}(\widetilde{\gamma}_{N}) = \int \frac{1}{2} a(\widetilde{\gamma}_{N}) |\widetilde{\widetilde{\gamma}}_{N}|^{2} - \frac{1}{n^{2}} U(\widetilde{\gamma}_{N})$$

Moreover, using again (3.36), by lemma 3.5 (c), $\widetilde{\gamma}_N$ satisfy the following equation

$$\mathbf{a}(\widetilde{\gamma}_{\mathrm{N}})\widetilde{\widetilde{\gamma}_{\mathrm{N}}} = \frac{1}{2} |\widetilde{\widetilde{\gamma}_{\mathrm{N}}}|^{2} \nabla \mathbf{a}(\widetilde{\gamma}_{\mathrm{N}}) - (\nabla \mathbf{a}(\widetilde{\gamma}_{\mathrm{N}}) \cdot \widetilde{\widetilde{\gamma}_{\mathrm{N}}}) \widetilde{\widetilde{\gamma}_{\mathrm{N}}} - \frac{1}{N^{2}} \nabla \mathbf{U}(\widetilde{\gamma}_{\mathrm{N}})$$

Therefore, setting $\gamma_N(t) = \widetilde{\gamma}_N(Nt)$, it follows that $\gamma_N(t)$ satisfy the equation $a(\gamma_N) \gamma_N = \frac{1}{2} | \dot{\gamma}_N |^2 \nabla a(\gamma_N) - (\nabla \gamma_N \cdot \dot{\gamma}_N) \dot{\gamma}_N - \nabla U(\gamma_N)$

Then (i) and (ii) of Theorem 1.1 are proved. By (3.37) and lemma 3.5 (a) we have that $\alpha N^2 < \int \frac{1}{2} |a(\gamma_N)| \dot{\gamma}_N|^2 - |U(\gamma_N)| < \beta N^2$

The above inequalities prove (iv) of theorem 1.1. Moreover, using again lemma 3.5 (c) and (3.36) we get

$$\alpha < \frac{1}{2} a(\widetilde{\gamma}_N) |\dot{\widetilde{\gamma}}|^2 + \frac{U}{N^2} (\widetilde{\gamma}_N) < \sigma$$
 for every te (0,1)

Therefore

$$an^2 < \frac{1}{2} a(\gamma_N) |\dot{\gamma}_N|^2 + U(\gamma_N) < \sigma N^2$$

Thus (iii) of theorem 1.1 is obtained with $E^- = \alpha$ and $E^+ = \sigma$. The last remark of theorem 1.1 follows by (3.13').

REFERENCES

- [BBF] P. PARTOLO, V. BENCI, D. FORTUNATO, Abstract critical point theorems and applications to some nonlinear problems with strong resonance at infinity, Nonlinear Anal. T.M.A., 7 (1983), 981-1012.
- [B₁] V. BENCI, Periodic solutions of Lagrangian systems on a compact manifold, preprint, MRC Technical Summary Report #2577 (1983).
- [B₂] V. BENCI, Closed geodesics for the Jacobi metric and periodic solutions of prescribed energy of natural Hamiltonian systems, preprint.
- [BCF] V. BENCI, A. CAPOZZI, D. FORTUNATO, Periodic solutions of Hamiltonian systems of prescribed period, preprint, MRC Technical Summary Report #2508 (1983).
- [BF] V. BENCI, D. FORTUNATO, Un teorema di molteplicità per un'equazione ellittica non lineare su varietà simmetriche, Proceedings of the Symposium "Metodi asintotici e topologici in problemi diff. non lineari", L'Aquila (1981).
- [BF] V. BENCI, P. H. RABINOWITZ, Critical point theorems for indefinite functionals, Inv. Math. <u>52</u> (1979), 336-352.
- [C] G. CERAMI, Un criterio di esistenza per i punti critici su varietà illimitate, Rendiconti dell'Accademia di Sc. e Lettere dell'Istituto Lombardo 112 (1978), 332-336.
- [G] E. W. C. VAN GROESEN, Applications of natural constraints in critical point theory to periodic solutions of natural hamiltonian systems, Preprint MRC Technical Summary Report #2593, (1983).
- [R $_1$] P. H. RABINOWITZ, Periodic solutions of Hamiltonian systems: a survey, SIAM J. Math. Anal. $\underline{13}$ (1982).
- [R₂] P. H. RABINOWITZ, Periodic solutions of large norm of Hamiltonian systems, J. of Diff. Eq. 50 (1983), 33-48.
- [R3] P. H. RAPINOWITZ, The mountain pass theorem: theme and variations, Proceedings of First Latin-American Seminar on Differential Equations de Figuereido Ed., Springer Verlag Lecture Notes.

[R₄] P. H. RABINOWITZ, On large norm periodic solutions of some differential equations, in "Ergodic Theory and Dynamical Systems", F. A. Katock, ed., Birkhaüser (1982), 193-210.

VB/ed

REPORT DOCUMENTATION	ON PAGE	READ INSTRUCTIONS BEFORE COMPLETING FORM	
1. REPORT HUMBER 2610	2. GOVT ACCESSION NO.	3. RECIPIENT'S CATALOG NUMBER	
A. TITLE (and Subsists) NORMAL MODES OF A LAGRANGIAN SYSTEM CONSTRAINED IN A POTENTIAL WELL		S. TYPE OF REPORT & PERIOD COVERED Summary Report - no specific reporting period 6. PERFORMING ORG. REPORT NUMBER	
7. AUTHOR(a)		6. CONTRACT OR GRANT NUMBER(a)	
V. Benci		DAAG29-80-C-0041	
Mathematics Research Center, U 610 Walnut Street Madison, Wisconsin 53706 11. CONTROLLING OFFICE NAME AND ADDRESS U. S. Army Research Office P.O. Box 12211 Research Triangle Park, North Ca	Visconsin Wisconsin arolina 27709	10. PROGRAM ELEMENT, PROJECT, TASK AREA & WORK UNIT NUMBERS Work Unit Number 1 - Applied Analysis 12. REPORT DATE December 1983 13. NUMBER OF PAGES 27 15. SECURITY CLASS. (of this report) UNCLASSIFIED 15a. DECLASSIFICATION/DOWNGRADING SCHEDULE	
16. DISTRIBUTION STATEMENT (of the Report) Approved for public release; distribution STATEMENT (of the electract entering)		er Report)	
18. SUPPLEMENTARY NOTES			

19. KEY WORDS (Continue on reverse side if necessary and identity by block number)

Lagrangian system, periodic solutions, minimax principle, Palais-Smale condition

20. ABSTRACT (Continue on reverse side if necessary and identify by block number)

Let a,U \in C²(Ω) where Ω is a bounded set in \mathbb{R}^n and let

 $L(x,\xi) = \frac{1}{2} a(x) |\xi|^2 - u(x),$ $x \in \Omega; \xi \in R^n$.

We suppose that a,U>0 for $x\in\Omega$ and that

 $\lim U(x) = + \cdot \cdot$

(Cont.)

ABSTRACT (Cont.)

Under some smoothness assumptions, we prove that the Lagrangian system associated with the above Lagrangian L has infinitely many periodic solutions of any period T.

FILMED
3-84

DTIC